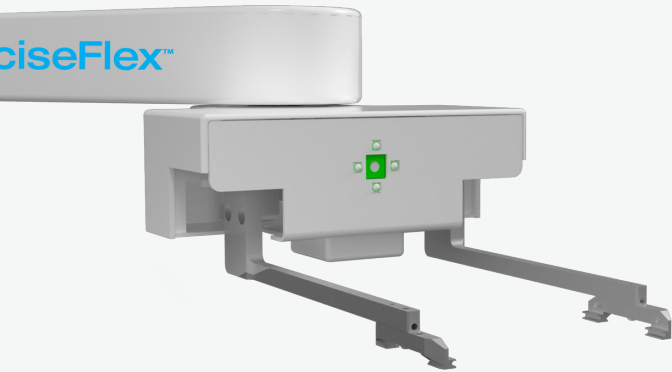


# IntelliGuide™ Vision - preliminary

Vision Made Easy for PreciseFlex Robots in Structured and Unstructured Environments



\*Gripper Fingers not included

Cameras embedded the gripper (forward and downward facing) enable less engineering effort, faster deployment, and shorter time-to-production.

## Simplify Vision Applications

Factory calibrated and ready to use out of the box. Simply specify offset to gripper fingers.

## Reduce Design, Eng. and Deployment Costs

Significantly reduces the time needed from system design to installation and deployment.

## Auto-Recovery When Change Happens

Automatic recovery and re-teaching of locations when things shift in the workspace.

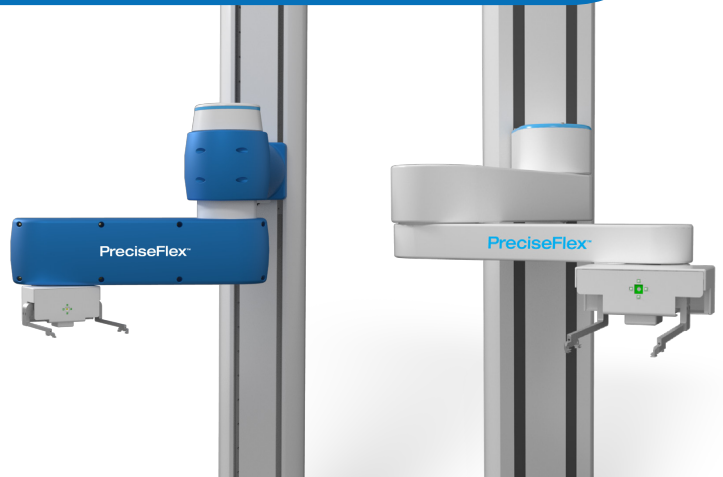
## Ideal for Roll-up Carts and AMRs

Easily locate objects in dynamic environments.

## TCP Command Server (TCS) Compatible

## Key Benefits

- Fast and easy deployment unlocks the best ROI
- Automatically adapt to changes in workspace
- Eliminate time consuming teaching for simple and complex applications
- Higher reliability with no external cables



PreciseFlex c10 Robot with IntelliGuide v60

PreciseFlex 3400 Robot IntelliGuide v23

## Auto-Teach

- Read ArUco Markers and determine offsets to hotels, instruments, magazines, fixtures etc.
- Quickly recover from changes in workcell without re-teaching tens or hundreds of locations.

## Barcode Reading

Read 1D and 2D barcodes. See specifications for complete list.



## Object Locator

- Geometric part locator tool for locating objects in 2D space.
- Quickly train objects and start picking from trays, conveyors, nests, etc.

## Image Sharpness

Returns image sharpness that enables focus adjustment by moving the robot closer to, or farther away from, the target.

## Image Capture

Capture time-stamped images when an event occurs and transfer for further analysis. Useful for trouble shooting of chain of custody.

## Additional Vision Tools Available

# IntelliGuide™ Vision - Specifications- preliminary

## Robot Compatibility

<b>IntelliGuide v23</b>	PreciseFlex 400*, PreciseFlex 3400*, PreciseFlex c10
<b>IntelliGuide v60</b>	PreciseFlex 3400*, PreciseFlex c10

\*Also compatible with these robots on Collaborative Linear Rail

## Specifications

<b>Cameras</b>	Forward Looking and Downward Looking
<b>Resolution</b>	5MP, H:2592, V:1944
<b>Pixel Size</b>	H:1.4 μ, V: 1.4 μ
<b>Lens</b>	6 mm Manual adjustment requires re-calibration
<b>Working Distance</b>	150 mm (as configured)
<b>Focal Length</b>	2.8 mm
<b>FOV (H):</b>	72°
<b>Lighting</b>	PWM Controlled LED lighting (White)
<b>Precision, Typical from static position at Working Distance</b>	±0.18 mm in X/Y/Z, ±0.19° in Rotation (results can vary with application)

## Barcode Formats 1D

Code39 (standard and extended)  
Code128 (standard and short)  
Code25 (ITF)  
Codebar (Codabar)  
EAN\_8  
EAN\_13  
UPC\_E  
UPC\_A  
CODE39Checksum  
Code39StartStop  
Code25Checksum  
Code93

## Barcode Formats 2D

PDF\_417 (standard and Micro)  
DATA\_MATRIX  
DATABAR  
PATCH\_CODES  
Aztec  
QR Code

## IntelliGuide v23

23N Gripping Force  
60 mm Stroke  
1.0 kg Payload (when friction is the only gripping force)  
Robot payload capacity must also be considered  
Picks SBS plates in portrait and landscape orientation

## IntelliGuide v60

60N Gripping Force  
40 mm Stroke  
3.0 kg Payload (when friction is the only gripping force)  
Robot payload capacity must also be considered

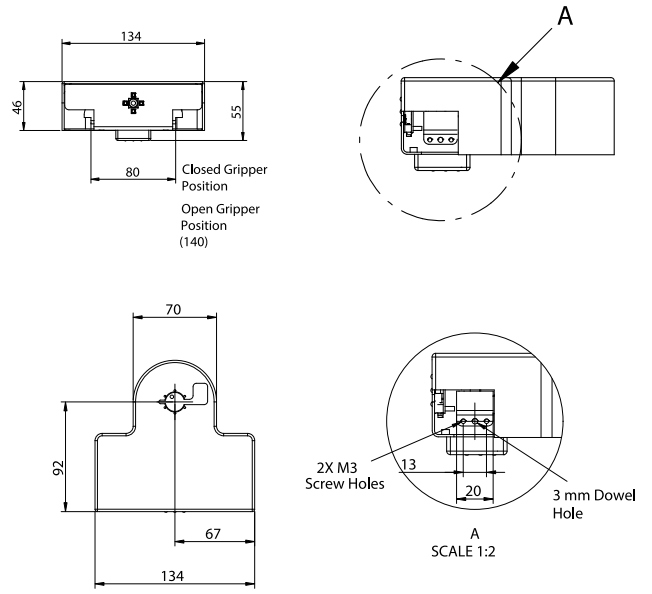
## Options

See IntelliGuide Accessories Datasheet  
ArUco labels for quick start  
Calibration plate  
SBS Plate fingers (for IntelliGuide v23)

## Software

Programming via Guidance Development Studio (GDS)  
Compatible with Guidance Programming Language (GPL)  
Compatible with TCS API

## Dimensions, IntelliGuide



## Dimensions, IntelliGuide

